

Dynamic Massive Parallel Computation Model for Graph Problems

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Introduction

- What is Massive Parallel Computing and why MPC
 - Computations on massive amounts of data
 - Traditional models are inadequate
 - MPC model captures the needs of computation at a massive scale
 - A collection of machines
 - communicate through indirect communication channels
 - Computation proceeds in synchronous rounds
- Limitations of MPC
 - Assumes to work on static datasets
 - Use of large volumes of resources

Introduction

- Dynamic algorithm and its benefits
 - Maintain a solution to a given problem throughout a sequence of modifications to the input data
 - Efficiently adjust the maintained solution
 - Detect whether modifications are needed almost instantly
 - Polynomial, and often exponential, speed-up
- Objective
 - Implement a Dynamic MPC (DMPC) algorithm
 - Test on a graph problem, Maximal Independent Set

Related Work

- **Classic MPC:**
 - $(1 + \epsilon)$ -approximate matching: $\tilde{O}(\sqrt{\log \Delta})$
 - Connected components: $\tilde{O}(\log D)$
- **DMPC:**
 - Maximal matching: $O(1)$
 - Connected components: $O(1)$
- **Maximal Independent Set**
 - Classic MPC: $\tilde{O}(\log \log \Delta)$
 - Dynamic: $O(\log^2 \Delta \cdot \log^2 n)$

Methodology

- MPC Model
 - A set of μ machines M_1, \dots, M_μ
 - Memory that fits up to S bits per machine
 - Exchange messages in synchronous rounds
 - Send and receive messages of total size up to S per machine per round
 - Input, of size N , stored across the different machines in arbitrary way
 - Output at most S bits per machine

Methodology

- Dynamic graph algorithm
 - Incremental: allow edge insertions only
 - Decremental: deletions only
 - Fully-dynamic: intermixed sequence of both
- Factors that determine the complexity of the dynamic algorithm
 - Number of rounds
 - Number of active machines per round
 - Total amount of communication per round

Methodology

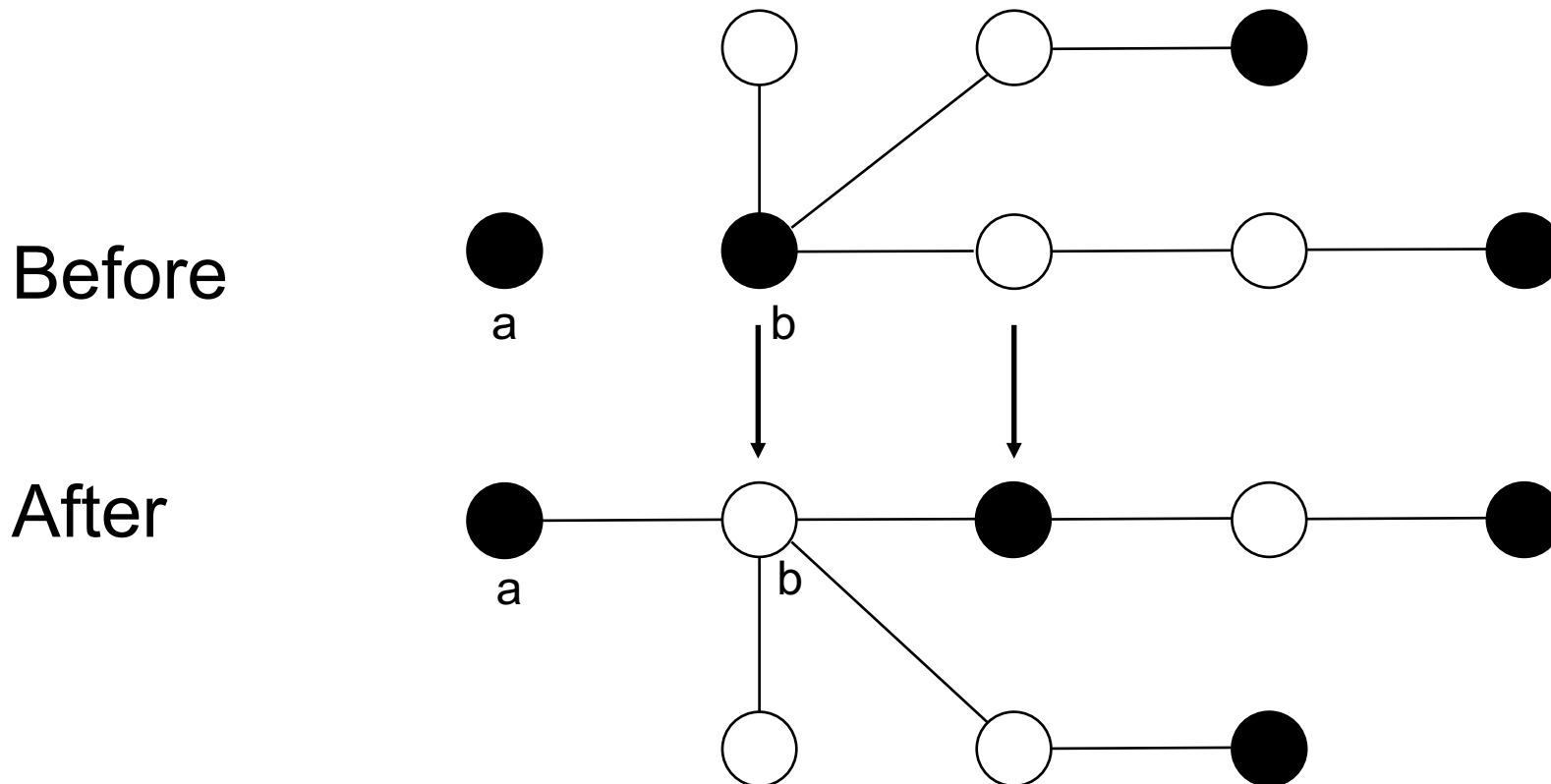
- Terminology of lexicographically first maximal independent set (LFMIS)
 - Graph $G(V, E)$
 - $n = |V|, m = |E|$
 - Ranking $\pi: V \rightarrow [0, 1]$
 - Add an alive vertex v to the MIS
 - Kill v and all of its alive neighbors
 - $LFMIS(G, \pi)$: subset of vertices that join the MIS
 - $\deg(v)$: degree of vertex v
 - $count(v)$: number of neighbors of vertex v that are in the MIS
 - $N^+(v)$: set of neighbors of v in the MIS
 - $N^-(v)$: set of neighbors of v not in the MIS
 - Assign ID $(1, \dots, n)$ to each vertex based on its ranking π

- Preprocessing
 - Input size N ; $O(\sqrt{N})$ memory per machine; $O(\sqrt{N})$ machines
 - $N = m + n$
 - $O(n/\sqrt{N})$ machines
 - Stored statistics about each vertex v
 - $\text{deg}(v)$
 - Whether in $LFMIS(G, \pi)$
 - $\text{count}(v)$
 - $N^+(v)$ & $N^-(v)$
 - Machine storing its neighbors
 - Vertices with consecutive IDs allocated together

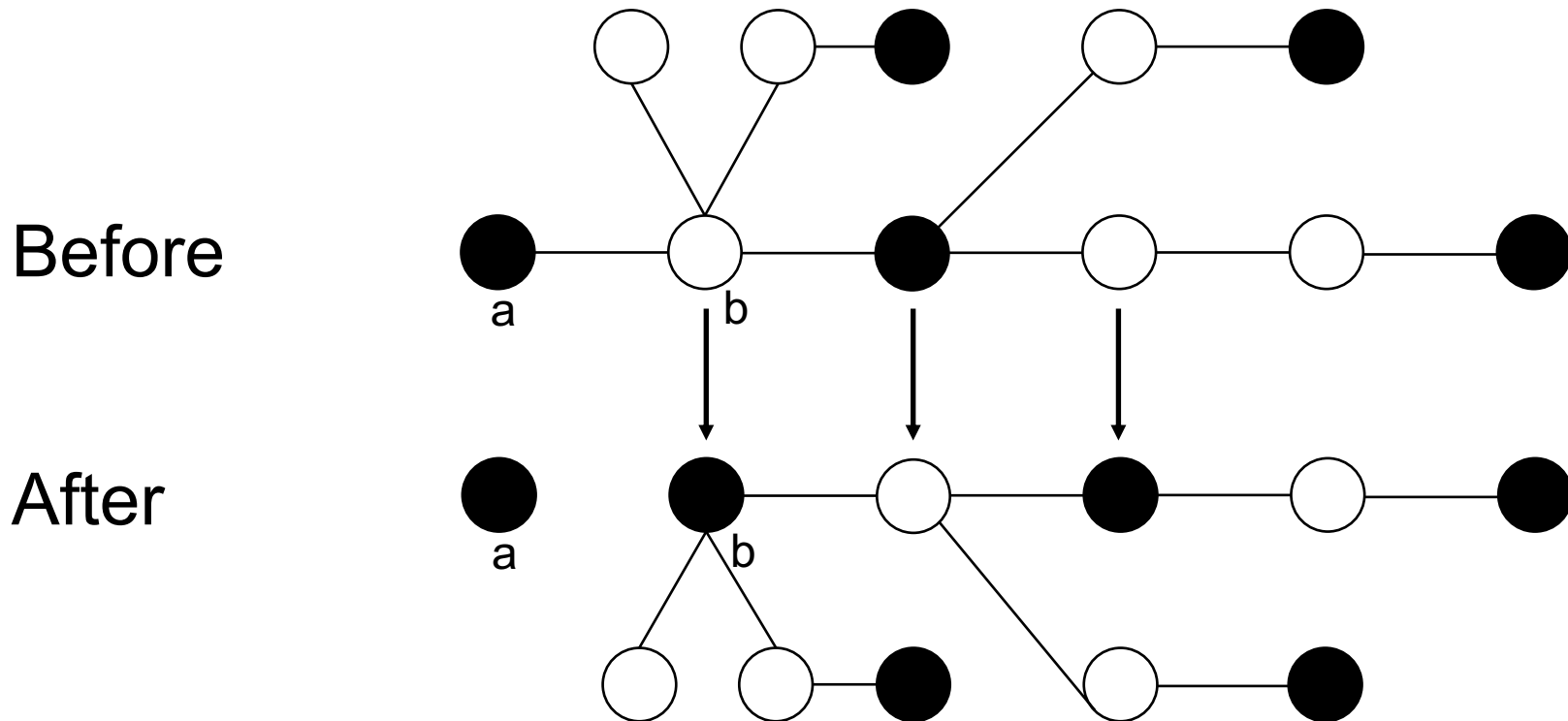
- Preprocessing
 - 1 coordinator machine: M_C
 - All updates are sent to it
 - Store additional information
 - Update history \mathcal{H} : last $O(\sqrt{N})$ updates
 - Corresponding machine storing statistics for each range of IDs
 - Memory available in each machine
 - Coordinate other machines to perform the update
 - Updated automatically

Methodology

- Insertion



- Deletion



Methodology

- For each update to the graph
 - Update vertex neighbors based on \mathcal{H}
 - Might move vertices to another machine if fit
 - Update each machine in a round-robin fashion
 - Updated after at most $O(\sqrt{N})$ updates

- Complexity of the dynamic algorithm
 - Number of rounds per update
 - Only fixed number of vertices need to be updated
 - Number of active machines & Total communication per round
 - Number of edge updates not yet updated: $O(\sqrt{N})$
 - Size of moved vertices: at most the memory of each machine, $O(\sqrt{N})$

Conclusion

- The fully-dynamic algorithm in the DMPC model maintains a maximal independent set in $O(1)$ rounds per update, while the number of machines that are active per round is $O(1)$, and the total communication per round is $O(\sqrt{N})$

1. What are the benefits of a dynamic algorithm?
2. What are the restrictions of the DMPC algorithm?
3. Is the use of a coordinator in the dynamic algorithm to simulate a centralized algorithm?

Thank you!